MIXED DIMENSIONAL COMPACTNESS WITH DIMENSION COLLAPSING FROM \mathbb{S}^{n-1} BUNDLE MEASURES.

SIMON P MORGAN

ABSTRACT. We provide a measure based topology for certain unions of C^2 rectifiable submanifolds of mixed dimensions in \mathbb{R}^n . In this topology lower dimensional sets remain in the limit as measures when higher dimensional sets collapse down to them. For example a decreasing sequence of spheres may have a limit consisting of just a point. The n-1 dimensional space of outward pointing vectors can be used for such a measure. It represents all C^2 rectifiable sets of codimension at least one of \mathbb{R}^n as rectifiable sets in $\mathbb{R}^n X S^{n-1}$ with n-1 dimensional Hausdorff measure. When viewed as (n-1)-rectifiable varifolds or currents in $\mathbb{R}^n X S^{n-1}$ they come equipped with compactness theorems. The projection of their limits to \mathbb{R}^n recovers the rectifiable sets of mixed dimensions giving the limits for the desired topology on subsets of \mathbb{R}^n . Both varifold and current compactness are required as there are sequences, such as honeycombs, that converge as varifolds but not as currents. Conversely sequences such as lifts of polyhedral approximations converge as currents but not as varifolds.

Contents

1. Introduction	2
1.1. Motivating example for this paper	2
1.2. Background	3
1.3. Statement of theorem 1.1	4
1.4. Outline of paper	4
2. The sphere bundle measure of submanifolds in \mathbb{R}^n	5
2.1. Definitions of outward vector lift	5
2.2. Examples of lifts	6
3. Varifold compactness for \mathbb{S}^{n-1} bundle measures	8
3.1. Definition of varifold and total first variation	8
3.2. Varifold compactness	8
3.3. Conditions on sets in \mathbb{R}^n so that the lifts converge as varifolds	9
4. Projecting sphere bundle measure limits to sets in \mathbb{R}^n	10
5. Currents	13
5.1. The Polyhedral Case	13
5.2. Definition of Rectifiable currents	13
5.3. Statement of current compactness theorem	14
5.4. Conditions on sets in \mathbb{R}^n so that the lifts converge as currents	14
5.5. The problem of mass cancellation in current compactness	15
5.6. Elimination of mass cancellation	15

Key words and phrases. Currents, Varifolds, Dimension collapsing.

6. Summary		18
7. Appendix		19
7.1. First Variat	ion	19
7.2. Homological	Boundary	19
7.3. Example of	varifold only convergence	19
References	·	20

1. Introduction

This paper is the second of two, the first of which [MS] provides an example (figure 1) of a physical optimization problem involving minimal surfaces and threads of viscoelastic fluids with prescribed boundary and initial conditions. This has a solution which is the limit of minimizers of an energy functional, that is the limit of images of harmonic maps. The regularity associated with minimizers, such as harmonic map images, can help establish existence of limits of such minimizers. The limiting process in our example has two features of interest. It involves dimension collapsing of the images of the harmonic maps, where the lower dimensional sets are part of the solution, and discontinuities can arise in bubbling. Although in our example each limit of images can be achieved as a point-wise limit by careful construction of a sequence of harmonic maps once it has been found [MS], a general sequence will not have a defined point-wise limit.

This, the second paper provides two versions of a topology that overcomes both the problem of requiring the lower dimensional sets to be kept in the limit, and the problem of discontinuities due to bubbling in a sequence of harmonic map images. This is done using sphere bundle measures (on $\mathbb{R}^n X \mathbb{S}^{n-1}$) to represent sets in \mathbb{R}^n and to take limits of sphere bundle measures rather than the underlying sets, then to project down in the limit. The sphere bundle measure compactness has the added advantage of providing a topology which compactifies certain unions of C^2 j-rectifiable subsets of \mathbb{R}^n with j varying from 0 to n-1, where the boundaries and singular sets are also C^2 rectifiable. Fortunately our motivating example consists of taking limits of sets which are C^2 (n-1)-rectifiable, as they are images of harmonic maps. More generally we would hope for the required regularity whenever we take sequences of minimizers of functionals.

1.1. Motivating example for this paper. Figure 1 shows a sequence of images of harmonic maps from varying annuli into \mathbb{R}^3 with fixed boundary circles [MS]. A topological cylinder can be seen shrinking down to two discs union a straight segment. Such a sequence could represent a physical optimization problem of a liquid film with elasticity and surface tension forming a minimum energy configuration. The surface tension causes area to be locally minimized resulting in the two discs, while the elasticity causes the residual thread connecting the two discs to remain.



Figure 1: Dimension collapsing

Conventional geometric measure theory provides measures and topologies with compactness and regularity theorems that represent the above sequence in terms of area measure. This will represent the cylinders and discs, but will miss the residual straight line segment. Our goal is to find a measure and a topology which will represent both the area measure and the straight line segment in the limit. This would enable geometric measure theory compactness and regularity theorems to be applied to these more general problems involving sequences of sets whose dimensions collapse in the limit.

We take a measure based on the normal or outward pointing vectors to obtain the desired concentration of measure around the straight line segments as curvature increases and becomes infinite. In the limit we obtain a circle of outward vectors concentrated at each point in the straight line segment, thus giving 2-dimensional measure along the length the segment. We will see in section 2 that outward vectors also allow boundary to be weighted, giving another way for a measure to capture dimension collapsing, for example when an interval shrinks in length down to a point. The two masses at each end of the interval coincide in the limit, leaving mass at the point.

This new topology requires, among other uniform bounds conditions, the set of outward vectors to be rectifiable. In our example application the sequence has this regularity by virtue of being images of harmonic maps. So in general, in applications we would take sequences of sets which are themselves minimizers of some functional which endows them with the necessary regularity to have rectifiable outwards vectors. Typically being C^2 almost everywhere, with C^2 boundary or singular sets will be sufficient to ensure outward vector regularity. See section 3 for necessary and sufficient conditions.

1.2. **Background.** Our approach and applications follow on from two approaches within the mathematics of minimal surfaces. The use of harmonic maps to find minimal surfaces [D] and the development of measure based compactness theorems, such as for varifolds [Al] and for currents [FF], in geometric measure theory. For introductions to the is field see [MF] for many examples, and [LY],[S] and [HS], give deeper treatments, with [F1] as the general case reference not written for the uninitiated. [Ma] covers sets from a measure theoretic viewpoint. The set of outward pointing vectors on a smooth subset of \mathbb{R}^n of any dimension will be an n-1 manifold on the \mathbb{S}^{n-1} bundle of \mathbb{R}^n . Thus can be treated as an (n-1)-rectifiable current or varifold in the \mathbb{S}^{n-1} bundle, $\mathbb{R}^n \times \mathbb{S}^{n-1}$. This enables current or varifold compactness to be used on the \mathbb{S}^{n-1} bundle so that a limit is obtained which can be projected down to \mathbb{R}^n .

The underlying objects of geometric measure theory are rectifiable sets. These have the following definitions:

Definition 1.1. Rectifiable sets

An m-dimensional set in \mathbb{R}^n is countably n-rectifiable if

$$M = M_0 \cup \left(\bigcup_{j=1}^{\infty} F_j \left(\mathbf{A}_j \subset \mathbb{R}^m \right) \right), H^m \left(M_0 \right) = 0, \text{and } F_j \left(\mathbf{A}_j \right) \to \mathbb{R}^n, \text{ are Lipschitz functions for } j=1,2,3.... [S. p 58]$$

This leads to the equivalent definition [S. p 59]

Definition 1.2. An n-dimensional set is countably n-rectifiable iff

 $M\subset \bigcup\limits_{j=0}^{\infty}N_{j}$ where $H^{m}\left(N_{0}\right)=0$ and each $N_{j},\,j\geq1$ is an m-dimensional embedded C^{1} submanifold of \mathbb{R}^{n} .

Any rectifiable current or rectifiable varifold has underlying rectifiable set on which the current or varifold has density > 0. Varifolds should be considered as rectifiable sets which have a measurable point-wise density [MF p11][F1, 2.9.12, 2.10.19], and unique approximate tangent cones almost everywhere. See [MF p28] for approximate tangent cones and [MF p92] for points without unique tangent cones. Currents, duals to forms, should be considered as sets with density and unique approximate tangent cones and orientation.

We also use the notion of C^2 k-rectifiable sets which were introduced by Anzellotti [An].

Definition 1.3. C^2 k-rectifiable are sets for which the $N_j s$ in definition 1.2 are embedded in C^2 submanifolds

These C^2 submanifolds will have C^1 lifts, enabling the lifts of the N_js to be rectifiable.

More specifically, our unions of rectifiable sets can be regarded as multivarifolds as introduced by Dao and Fomenko[DF][Fo]. They in fact used these multivarifolds to express limits of manifolds with dimension collapsing just as in our example. [Fu][F2] show these can be the projections into \mathbb{R}^n of currents which can be seen as representing curvature measure of the underlying sets. This is precisely the measure that concentrates around parts of manifolds that collapse in dimension.

We can now state the main results of this paper:

1.3. **Statement of theorem 1.1.** This theorem gives the main gaol of the paper to provide a measure based topology that captures dimension collapsing.

Theorem 1.4. Let M_i be a sequence of unions of C^2 j-rectifiable sets of positive H^j measure in \mathbb{R}^n , (with j taking on different values; $0 \le j \le n-1$) where each of the outward vector lifts, \widetilde{M}_i , will all be n-1 rectifiable sets in $\mathbb{R}^n X \mathbb{S}^{n-1}$.

If the corresponding sequence M_i of outward vector lifts converge as n-1 rectifiable currents or n-1 rectifiable varifolds in $\mathbb{R}^n X \mathbb{S}^{n-1}$, then the image M of the projection of the limit current or varifold, will itself be a union of j-rectifiable sets in \mathbb{R}^n , $(0 \le j \le n-1)$. Also all dimension collapsing will be captured. If the first variation of the lifts is uniformly bounded then the lifts may converge as varifolds, if the homological boundary is uniformly bounded then the lifts may converge as currents

See sections 3 and 5 for conditions on when convergence as varifolds or currents will occur.

1.4. **Outline of paper.** In section 2, we examine the process of taking the outward vectors for smooth submanifolds with boundary of all dimensions in \mathbb{R}^n . These give rise to a n-1 dimensional set in $\mathbb{R}^n X \mathbb{S}^{n-1}$, the trivial sphere bundle over \mathbb{R}^n . We see why we need to represent more than just the vectors normal to tangent planes by including extra vectors on boundary points. This ensures the measure captures dimension collapsing

Then in section 3 we examine these n-1 dimensional sets in $\mathbb{R}^n X \mathbb{S}^{n-1}$ as rectifiable n-1 varifolds, which gives them a topology and compactness theorem. For

compactness they need to meet strict conditions, finite first variation, that would not be met for example by successive polyhedral approximations to any smooth submanifold. We also explore more fully the conditions on M such that the lift constructed in section 2 will be rectifiable

Section 4 shows how sets in \mathbb{R}^n can be obtained by projecting n-1 rectifiable varifolds from $\mathbb{R}^n X \mathbb{S}^{n-1}$ to \mathbb{R}^n . This process is not the inverse of the process in section 2 as extra lower dimensional sets representing boundary or produced as a side effect. Specifically, n-1 rectifiable varifolds project down to a union of rectifiable varifolds of dimensions that can vary from 0 to n-1.

Section 5 shows why polyhedral approximations in \mathbb{R}^n represented as n-1 rectifiable varifolds in $\mathbb{R}^n X \mathbb{S}^{n-1}$ will not satisfy the conditions for varifold compactness, but as n-1 rectifiable currents they can satisfy conditions for rectifiable current compactness. This is because the sets representing normal vectors to polyhedra cannot be of finite first variation if polyhedral edge length is infinite. However current compactness has no first variation condition, so with appropriate 'filling in' a polyhedron with infinite edge length but finite total distributional curvature (edge length integral of dihedral angle) can be represented as an n-1 rectifiable current.

However there is one drawback of current limits that varifolds do not have. Mass can disappear in the limit due to cancellation of measures with opposite orientations, or due to homothetic contraction of manifolds such as tori which have degree zero Gauss maps. A method is given to overcome this using the coarea formula to further fill in the lifts until each lift is a union of \mathbb{S}^{n-1} s.

2. The sphere bundle measure of submanifolds in \mathbb{R}^n

We give a general construction (see figures 2 to 5) for lifts of a union of submanifolds of mixed dimensions from 0 to n-1. These lifts will then be represented as measures in $\mathbb{R}^n X \mathbb{S}^{n-1}$ where geometric measure theory compactness theorems will give limits. We will not address codimension zero subsets as these can be represented by taking \mathbb{R}^n as an isometrically embedded subset of \mathbb{R}^{n+1} and applying the construction within \mathbb{R}^{n+1} instead.

2.1. Definitions of outward vector lift.

Definition 2.1. An outward vector to a j-dimensional rectifiable set M in \mathbb{R}^n at a point p is the set of unit vectors in the tangent space of \mathbb{R}^n which has a zero or negative inner product with any vector in the approximate tangent cone of M at p.

In general $(H^j$ a.e.) this will be the normal vectors making up an n-1-j dimensional set in $\mathbb{R}^n X \mathbb{S}^{n-1}$. These unit vectors can be represented as points in \mathbb{S}^{n-1} . Let O(p) be the set of all outward vectors at a point p, $O(p) = \{ \mathbf{x} \in \mathbb{S}^{n-1} : \mathbf{x}.\mathbf{v} \leq 0, \forall \mathbf{v} \in X \}$ where $X \subset \mathbb{S}^{n-1}$ is the link of the approximate tangent cone at p.

Definition 2.2. The special case lift of a set M with a unique approximate tangent cone everywhere is given by $\widetilde{M} = \{(p, O(p)) \subset \mathbb{R}^n X \mathbb{S}^{n-1} : p \in \overline{M}\}$ where \overline{M} is the closure of M. We can think of this as endowing open sets as with the boundary of their closure.

This definition only makes sense where \overline{M} has a unique approximate tangent cone [MF p28] [S] [F1]. Call C the set of all points in \overline{M} with unique tangent cones. The approximate tangent cone of \overline{M} at p can be thought of as a generalization of

a linear approximation to \overline{M} at p. It allows for singularities such as boundary or sections of planes coming together. For an m-submanifold the cone will be the cone of a link which will be an m-1 manifold in the unit sphere in the ambient space.

It is known that n-rectifiable sets have tangent spaces almost everywhere. Therefore $\overline{M} - C$ is a set of zero measure, with respect to the dimension of \overline{M} . See [MF p 92] for a point without a unique approximate tangent cone.

So for all points, including those that do not have unique tangent cones we define.

Definition 2.3.
$$Oa(q) = \{ (\mathbf{v} \in \mathbb{S}^{n-1}) : \mathbf{v} \notin \{ \mathbf{y} : \forall r \exists x_r \in \overline{M} \cap B_{q,r} : \mathbf{y}.\overrightarrow{x_r - q} > 0 \} \}$$

Definition 2.4. The lift
$$\widetilde{M} = \{(p, O(p)) \cup (q, Oa(q)) : p \in C, q \in \overline{M} - C\} \subset \mathbb{R}^n X \mathbb{S}^{n-1}$$
.

Remark: In general $Oa(p) \neq O(p)$ where both exist. For example take a point p on a circle in \mathbb{R}^2 . O(p) will consist of two normal vectors, but Oa(p) consists only of the outward pointing vector. In fact for a point p on the surface of a catenoid as in figure 1, $Oa(p) = \emptyset$.

Remark: In sets which are smooth embeddings of polygonal or simplicial complexes, i.e.: the usual singular complexes, we do have a unique approximate tangent cone everywhere.

Remark: Note that as the lifts are to be represented as varifolds, the closure Oa(p) is equivalent as a varifold to Oa(p).

For technical reasons, to use current compactness, we also define a 'filled in' version of the lift, \widetilde{M}_F to make the lift homologically and topologically boundariless. Any remaining boundary on the lift is filled in fiber by fiber. This means that there is a mass of maximum that of hemisphere of the appropriate dimension added in each fiber. Also the lift is filled in to ensure that the lift can be expressed as a union of spheres of degree 1 under the projection map onto \mathbb{S}^{n-1} for theorem 5.1. This deals with cusps and non-manifold singularities where odd numbers of half hyperplanes come together. Call these extra points F. Now we can define, for use in thm 5.1 (and see figure 4):

Definition 2.5. The lift,
$$\widetilde{M}_F = \widetilde{M} \cup F$$

Theorem 2.6. :
$$H^{n-1}(\widetilde{M}) \ge H^{n-1}(\mathbb{S}^{n-1})$$
. For all j-rectifiable $M, j < n$.

Proof. Take the convex hull of the \overline{M} . Every strictly convex point of the hull will be in \overline{M} , because \overline{M} is compact. Whether such a point is in C or $\overline{M} - C$, and will have an outward vector lift locally containing the outward vector lift of the convex hull at those points. Every unit vector in \mathbb{R}^n (representable as a point in \mathbb{S}^{n-1}) will occur in the outward vector lift of p for at least one p.

2.2. **Examples of lifts.** For any compact boundariless smoothly embedded n-1 manifold M in \mathbb{R}^n .

 $\widetilde{M} = \{(x, \mathbf{v}), (x, -\mathbf{v}), x \in M, \mathbf{v} \in \mathbb{S}^{n-1}, \mathbf{v} \in TM_x \perp\} \subset \mathbb{R}^n \mathsf{X} \mathbb{S}^{n-1}$ See figure 2 for the lifts of a torus and a sphere embedded in \mathbb{R}^3 .

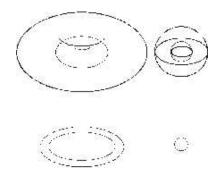


Figure 2: Lifts of normal vectors of M

Note that in each case \widetilde{M} is a double cover of M.

We now show the outward vectors and the lift of an interval collapsing down to a point to see how the boundary measure remains at the point.

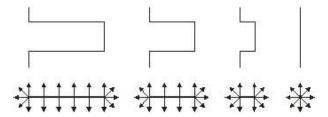


Figure 3: Lifts of outward vectors for dimension collapsing with boundary.

Figure 3 shows a sequence of line segments in \mathbb{R}^2 with their outward pointing vectors, and the lifts of those vectors to $\mathbb{R}^2 X \mathbb{S}^1$ are schematically represented above The \mathbb{S}^1 component is represented vertically.

In the case of a polygon collapsing, the outward pointing vectors at the vertices would end up leaving measure at a point in the limit. See the outward pointing vectors of the right angle as shown in figure 4. The vertical section above the right angle would remain under homothetic contraction. This is in addition to the vertical sections above the boundary points.

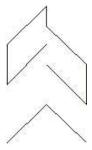


Figure 4: Lift of outward pointing vector of a right angle

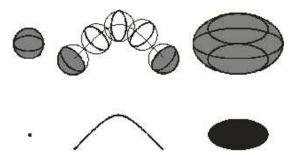


Figure 5: Outward vector lifts of a point a curve and a disc in \mathbb{R}^3

Figure 5 shows a different kind of schematic presentation of outward vector lifts to $\mathbb{R}^3X\mathbb{S}^2$. Because the lift is in a 5-dimensional space, it has been smoothed out in the figure 5. The lifts are not smooth as they appear, because in reality the lift of outward vectors at the boundary meet the lift of vectors near the boundary orthogonally as in figures 3 and 4. Topologically however, figure 5 gives the correct impression.

The point, the curve and the discs all have lifts that are topological surfaces in $\mathbb{R}^3 \mathbb{X}^2$. As every vector is outward from a point, the representation of the point is simply the whole sphere. The points in the interior of the curve are represented by copies of \mathbb{S}^1 as the normal vectors to the tangent space. Each boundary point of the disc lifts to a semicircle of points.

3. Varifold compactness for \mathbb{S}^{n-1} bundle measures

3.1. Definition of varifold and total first variation. The following is taken from Allard [Al].

A k-varifold on N, an smooth n-manifold, is a radon measure on the bundle over N whose fiber at each point p of N is the Grassmann manifold of k dimensional hyperplanes in the tangent space to N at p. A rectifiable integral k-varifold is strongly approximated by a positive integral linear combination of varifolds corresponding to continuously differentiable k-dimensional submanifolds of N.

 $IV_k(U)$ is the set of k-rectifiable integral varifolds on U,a open subset of N. |V| is k-dimensional Hausdorff measure of the k-dimensional set $M \subset U \subset N$ corresponding to V. $||\partial V||$ is the total first variation of the k-dimensional Hausdorff measure of M.

Note:
$$\|\partial V\| = \int_{\widetilde{M}_V} \|\overrightarrow{H}\| dH^k + \int_{\partial \widetilde{M}_V} dH^{k-1}$$
, is the total first variation where \overrightarrow{H}

is the mean curvature vector of M, in the distributional sense in the integral as described in the proof.

3.2. Varifold compactness.

Theorem 3.1. Suppose U is an open subset of \mathbb{R}^n , G_1 , G_2 , ... are open subsets of U, $U = \bigcup_{i=1}^{\infty} G_i$ and l_1 , l_2 , ... are nonnegative real numbers. Then $IV_k(U) \cup \{V : (\|V\| + \|\partial V\|)(G_i) \le l_i\}$ is compact.

$$IV_k(U) \cup \{V : (\|V\| + \|\partial V\|)(G_i) \le l_i\}$$
 is compact

This means that the space of uniformly finite mass and finite first variation k-rectifiable integral varifolds is compact. Intergal varifolds have positive integer density almost everywhere. So we now need to determine which sequences in \mathbb{R}^n will have lifts that converge as varifolds.

3.3. Conditions on sets in \mathbb{R}^n so that the lifts converge as varifolds. Conditions (3.3.i) and (3.3.ii) also apply for current compactness, but we will see in section 5 that condition (3.3.iii) changes for currents.

(3.3.i) Sets and their boundaries, and lower dimensional faces, are C^2 -rectifiable. This will ensure that the lifts are rectifiable as long as they have finite mass.

(3.3.ii) Sets and their boundaries, and lower dimensional faces, have uniformly bounded finite mass and finite integrals of principle curvatures (including distributional). This keeps the mass of the lifts uniformly bounded. Notice that we need to use distributional curvature. Consider the example of a polygon in \mathbb{R}^3 , each point on the face lifts to two points in $\mathbb{R}^3 X \mathbb{S}^2$, each point on an edge contributes a semicircle and each vertex contributes a portion of a sphere depending on the exterior angle of the polygon.

In general for a set M of dimension j the curvature bounds affect the Jacobian [S: section 8] of the lift.

$$(3.1) \qquad \qquad \prod_{1 \le k \le j} \sqrt{1 + \rho_k^2}$$

where ρ_k is a principle curvature in a direction k making up a local basis of TM, the tangent space of M in \mathbb{R}^n .

Consider the lift to the sphere bundle of each of the j directions in TM. For each k the lift has an identity component in an \mathbb{R}^n direction, and a component in the \mathbb{S}^{n-1} direction. Each directional derivative therefore has a component of 1 and a component equal to the curvature of M in the k direction. The lift of the outward vectors is in fact the space of orthogonal vectors to the lift in the fiber \mathbb{S}^{n-1} .

For the interiors of the manifolds and the boundaries this gives;

$$(3.2) \sum_{j} \left(\int_{M_{j}} \varpi^{n-j-1} \prod_{1 \leq k \leq j} \sqrt{1 + \rho_{k}^{2}} dH^{j} + \int_{\partial M_{j}} \frac{\varpi^{n-j}}{2} \prod_{1 \leq k \leq j-1} \sqrt{1 + \rho_{k}^{2}} dH^{j-1} \right) < L$$

where M_j is the union of j-dimensional manifolds of M, and ϖ^n is the volume of the unit n sphere. So for the sequence M_i this must be a uniform bound. Now there is an additional term for interior non-smooth points. This can be given by

(3.3)
$$\sum_{j} \int_{S \subset M_j} \varpi^{n-j} K dH^{j-1} < L$$

where S is the non-smooth singular set, and K represents the distributional curvature on that set. In the case of j = 2, K is just the exterior dihedral angle.

(3.3.iii) Sets have bounds on the integrals of the derivatives of curvature.

The lifts must have uniformly finite first variation. This requires bounds on the integrals of the derivatives of curvature on the M_i and finite boundary mass. Also there must be finite mass on singular sets such as polyhedral dihedral angle. This is because, as illustrated in figures 3 and 4 the lifts of non-smooth points will be non-smooth. Furthermore the lift of a small dihedral angle in the case of j=2, will involve dihedral angles in the lift equal to $\frac{\pi}{2}$. In other words lifting makes first

variation worse, by an unbounded factor. See section 5 on currents to see how to combat this drawback of varifolds compactness.

4. Projecting sphere bundle measure limits to sets in \mathbb{R}^n

The limiting process in the previous section gives rise to limit with an (n-1)-dimensional Hausdorff measure in $\mathbb{R}^n X \mathbb{S}^{n-1}$. When we project down to \mathbb{R}^n locally we may obtain anything from zero to n-1 dimensional Hausdorff measure depending on the rank of the projection map. The rank of the map at a point depends upon how many basis vectors of the tangent space as subset of $\mathbb{R}^n X \mathbb{S}^{n-1}$ lie in the \mathbb{R}^n directions and how many lie in the \mathbb{S}^{n-1} . In fact the rank is just the number of basis vectors that lie in the \mathbb{R}^n directions.

Accordingly say we have a limit varifold, we can decompose it into components each of which is n-1 rectifiable and has a fixed rank under projection to \mathbb{R}^n .

Theorem 4.1. An (n-1)-rectifiable set A in $\mathbb{R}^n X \mathbb{S}^{n-1}$ can be decomposed into n-1 different (n-1)-rectifiable sets, A_i , $(0 \le i \le n-1)$, where the tangent space of A_i at each point intersects the tangent space of \mathbb{S}^{n-1} in i-dimensional space.

Proof. This can be shown using the fact that an (n-1)-rectifiable set can be defined in terms of being a subset of a countable union of C^1 (n-1)-dimensional submanifolds (Def. 1.2). It is clear that each subset of fixed rank under the projection map is itself (n-1)-rectifiable as it is contained in the original union of submanifolds.

Now each of these sets has a projection so we need to show that each projection is rectifiable of the correct dimension. We will prove this by contradiction.

Theorem 4.2. Each of the A_is above projects down to an (n-1-i)-rectifiable set $p(A_i) \in \mathbb{R}^n$.

Proof. First we show $p(A_i) \in \mathbb{R}^n$ is rectifiable as it is a projection of a rectifiable set. As the projection of a C^1 submanifold is a C^1 submanifold then the projection is a rectifiable set using definition 1.2.

The coarea formula [F1: 3.2.32, 3.2.31] relates the measures of the varifolds and their projections up to sets of measure zero in the lift and in the projection. Therefore we can now proceed to write down varifolds in \mathbb{R}^n in terms of the limit of lifts.

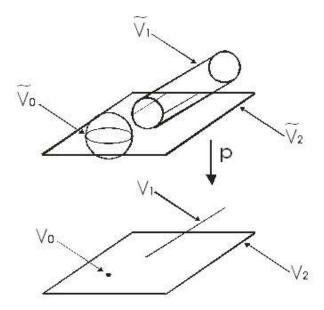


Figure 6: Decomposition of part of a limit varifold and projections

Figure 6 shows how a part of a limit of lift varifolds \widetilde{V} of density 1 can be represented as a varifold:

$$\widetilde{V} = \sum_{i=0}^{n-1} \widetilde{V}_i$$
 in the case $n=3$.

Also the projections are shown in \mathbb{R}^3 of the underlying sets of the lift varifolds, which become the underlying sets for V_0 , V_1 , V_2 . As the point underlying V_0 and part of the line segment underlying V_1 are contained in the planar region underlying V_2 , we can see that the limit of lifts in $\mathbb{R}^n \times \mathbb{S}^{n-1}$ contains more information than just the set.

We can define the V_i s in alternate ways. First consider the following simple equation that defines varifolds V_i in terms of varifold \widetilde{V}_i .

$$V_{i}\left(f\right) = \frac{1}{\varpi^{n-1-i}} \int_{x \in \widetilde{V}_{i}} f \circ p dH^{n-1}\left(\mathbb{R}^{n} \mathsf{X} \mathbb{S}^{n-1}\right)$$

Recall ϖ^n is the volume of the unit n sphere.

We shall now give a construction for the Vis only terms of \widetilde{V} . Using $\theta_{\widetilde{V}}$ to represent the density of \widetilde{V} , which will be integer multiplicity almost everywhere, we can use modified versions of 4.1 to obtain:

$$(4.2) \quad V_0\left(f\right) = \frac{1}{\varpi^{n-1}} \int_{x \in \mathbb{R}^n} f(x) \left(\int_{\left(p^{-1}(x) \cap \widetilde{V}\right)} \theta_{\widetilde{V}}(p^{-1}(x)) dH^{n-1}(\mathbb{S}^{n-1}) \right) dH^0\left(\mathbb{R}^n\right)$$

$$(4.3) \quad V_1\left(f\right) = \frac{1}{\varpi^{n-2}} \int_{x \in \mathbb{R}^n} f(x) \left(\int_{\left(p^{-1}(x) \cap \widetilde{V}\right)} \theta_{\widetilde{V}}(p^{-1}(x)) dH^{n-2}(\mathbb{S}^{n-1}) \right) dH^1\left(\mathbb{R}^n\right)$$

$$(4.4)$$

$$V_{i}(f) = \frac{1}{\varpi^{n-1-i}} \int_{x \in \mathbb{R}^{n}} f(x) \left(\int_{\left(p^{-1}(x) \cap \widetilde{V}\right)} \theta_{\widetilde{V}}(p^{-1}(x)) dH^{n-1-i}(\mathbb{S}^{n-1}) \right) dH^{i}(\mathbb{R}^{n})$$

We can show why each double integral picks out just the measure that is desired. In finding V_j , the inner integral takes H^{n-1-j} measure. This will eliminate any contribution to a V_k for k > j, as the fibers above each point will have zero H^{n-1-j} measure. Similarly the outer integral will eliminate contributions to a V_k for k < j. This is because although on points in $supp(V_k)$ a fiber will have infinite H^{n-1-j} measure, this will only occur on a set zero H^j measure on \mathbb{R}^n

Notice that for varifolds of dimension less than n-1 their underlying rectifiable set can be infinite. This is because there is no lower bound on the volumes of mass in each fiber. This is caused for example with a polyhedral approximation. The lengths of edges can go to infinity. So these are, in a sense, false projections as they correspond not to dimension collapsing such as threads in figure 1 but curvatures. Now [F1 3.2.31] allows for a cut off to be made so that only a subset of the projection is taken, that is those points that have more than a critical lower bound of mass. This new projection is then still rectifiable, and will then have finite mass. Call these varifolds, $V_i \mid_m$, that represent varifolds whose lift fibers all have at least mass m.

We have now proven part of theorem 1. The case where the first variation of the lifts of a sequence of sets is uniformly bounded. In the next section we will see that this is a limiting and avoidable restriction on sets, as long as certain types of non-manifold point singularities are bounded.

Remarks:

- According to the area and coarea formulae there will be a discrepancy between 4.1 on the one hand and 4.2 to 4.4 on the other. The map p^{-1} always has a Jacobian greater than one (by virtue that p is a projection) and less than infinity (because the measure of \tilde{V} is finite). As we are not using density information on the V_i s, this discrepancy is not important.
- The final stage is to take the support of each V_j to obtain the limit rectifiable set as desired. We may not get integer multiplicity of the varifolds V_j , so the underlying rectifiable set is a better canonical limit object, rather than the measure. One set can represent everything, but as measures, n-1 separate measures are needed to represent all of the set in \mathbb{R}^n , although in the sphere bundle one measure can represent the union. In particular varifolds representing boundary will have density of $\frac{1}{2}$ in general when no dimension collapsing occurs.
- In general the geometric relationship between the sets in \mathbb{R}^n and their lifts to outward pointing vectors in $\mathbb{R}^n\mathsf{X}\mathbb{S}^{n-1}$ may break down in the limit. Under the right conditions in the sequence of sets in \mathbb{R}^n , such as smoothly embedded connected submanifolds without boundary and with uniformly bounded curvature

everywhere, we might expect the limit of the lifts in $\mathbb{R}^n \times \mathbb{S}^{n-1}$ to represent the outward pointing vectors of its projection into \mathbb{R}^n . This would enable us to carry over regularity information from the sequence of sets in \mathbb{R}^n to its limit under our process. We can conjecture that such theorems can be proven using basic geometric measure theory on the tangent space of the lift varifolds, but are beyond the scope of this paper.

5. Currents

5.1. The Polyhedral Case. Here we explore the consequences of the need for a uniform bound on the integrals of derivatives of curvature in order for the first variation of the lifts to be uniformly bounded for varifold compactness. The worst case for derivatives of curvature are where the curvature concentrates around small regions rather than being evenly distributed over a manifold. In the limit this gives polyhedra, so we will now explore the lifts of polyhedra and see how to deal with them as measures in the sphere bundle.

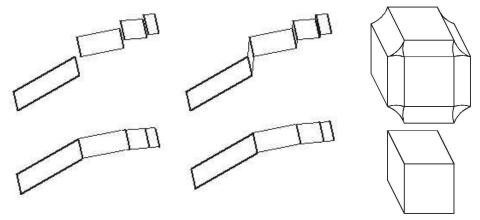


Figure 7: Polyhedra and their lifts

Figure 7 shows two copies of a polyhedral strip and a cube in \mathbb{R}^3 below with graphical representations of their various lifts above. Top left shows a normal vector lift of the polyhedral strip, showing that two boundary components lie in the fiber above an edge. Top middle shows how outward vectors at each edge lift to fill in the discontinuities in the lift on the left removing much of the new boundary. Note here that the fiber above every point in the edge is filled in between the directions of the adjacent faces. In fact the filled in part meets lifts of the adjacent edges orthogonally. This adds first variation to the lift proportional to the length of the edges. This means that varifold compactness in section 3 will not work for sequences polyhedral approximations of smooth surfaces whose edge lengths will tend to infinity.

5.2. **Definition of Rectifiable currents.** An n-dimensional rectifiable current in U is a continuous linear functional on $D^n(U)$, the space of smooth n-forms with compact support in U. These currents are denoted $D_n(U)$. For n > 0 the currents can be viewed as generalizations of the n-dimensional oriented submanifolds M having locally finite H^n -measure in U. Given such an M with an orientation ξ , we can write $\xi(x) = \pm \tau_1 \wedge ... \wedge \tau_n \, \forall x \in M$ where $\tau_1 \wedge ... \wedge \tau_n$ is an orthogonal basis

for T_xM . Additionally, just as with rectifiable n-varifolds we can endow M with a density function $\theta(x)$, a positive locally integrable function on M. Then we have the corresponding n-dimensional current T where:

$$T(\varpi) = \int_{M} \langle \varpi(x), \xi(x) \rangle \theta(x) dH^{n}, \ \varpi \in D^{n}(U)$$

We can define a boundary current $\partial T(\varpi) = T(d\varpi)$ in accordance with Stokes's theorem. When $\theta(x)$ is integer valued H^n almost everywhere we saw that the current is integer multiplicity.

5.3. **Statement of current compactness theorem.** The Federer-Fleming current compactness theorem [S],[FF] is as follows:

Theorem 5.1. Suppose T_j is a sequence of integer multiplicity rectifiable n-currents in \mathbb{R}^{n+k} and ∂T_j are integer multiplicity rectifiable n-1 currents in \mathbb{R}^{n+k} and W is a compact subset of \mathbb{R}^{n+k} , $\sup_{j\geq 1}(M_W(T_j)+M_W(\partial T_j))<\infty$ then there will be a subsequence that converges weakly in W to a rectifiable current T, which is also an integer multiplicity rectifiable n-dimensional current. $M_W(T)$ is the mass of the current T in a compact set W and is given by $M_W(T)=\sup_{\varpi}|T(\varpi)|, \varpi\in D^n(W), |w(x)|\leq 1, \forall x\in W$. Weak convergence is in the obvious sense, $T_j\to T\Leftrightarrow \lim_{j\to\infty}(T_j(\varpi))=T(\varpi), \forall \varpi\in D^n$.

5.4. Conditions on sets in \mathbb{R}^n so that the lifts converge as currents. Current compactness differs from varifold compactness in one key way. First variation is not required to be bounded, but homological boundary volume is. Homological boundary can exist locally with no first variation, for example see appendix. This occurs when orientation is assigned and for example half spaces come together, such as a Y-singularity. The induced boundaries on each of the three parts where they cannot all cancel.

The filled in lifts do satisfy current compactness conditions if the unfilled lifts do. The filling in contributes mass according to the distributional curvature of the M_i , in the surface case. So the hypotheses of bounded curvature integrals including distributional curvature will suffice to ensure current compactness.

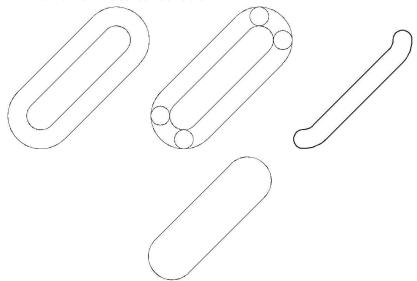
We need conditions 3.3.i and 3.3.ii, but instead of 3.3.iii we need to add a hypothesis that the topologically singular set, such as Y-singularities must have a uniformly finite mass lift. However it weakens a hypothesis. The geometrically singular set (approximate tangent cones have a dihedral angle) can now be infinite as long as the integral of dihedral angle is uniformly bounded as is the case with certain sequences of polyhedral approximation(this was covered by 3.3.ii). Now we can write conditions on sets for the lifts to converge as currents:

- (5.4.i) Sets and their boundaries, and lower dimensional faces, are C² rectifiable. (5.4.ii) Sets and their boundaries, and lower dimensional faces, have uniformly bounded finite mass and finite integrals of principle curvatures (including distributional).
- (5.4.iii) The topologically singular set, such as Y-singularities, must have a uniformly finite mass lift.

Note that for unions of non-singular manifolds current compactness is easier to achieve in the lifts than varifold compactness.

5.5. The problem of mass cancellation in current compactness. Say we have a sequence of oriented codimension 1 manifolds, with hypotheses fulfilled. We can see two simple ways mass can be cancelled in the limit. One is by two submanifolds converging to each other on a set of positive measure with opposite cancelling orientations. Another is under homothetic contraction. Take a torus in \mathbb{R}^3 with an orientation. Allow the lift to have the same orientation. Under homothety the limit of the lift will correspond to the push forward of the current under the Gauss map, as all vector directions are represented in the fiber above the center of the homothety in \mathbb{R}^3 . As the degree is zero this will mean that the current will cancel to zero in the limit. This does not give us any record of dimension collapsing, in terms of residual measure. The next section gives a method to overcome this problem under certain circumstances.

5.6. Elimination of mass cancellation.



 $\textbf{Figure 8: } \mathbf{M} \in \mathbb{R}^2 \textbf{, } \widetilde{\mathbf{M_F}}, \ \widetilde{\mathbf{M_F}} \cup \left(\underset{i=1}{\overset{n}{\cup}} \mathbb{S}^1_i \right) = \underset{j=1}{\overset{m}{\cup}} \mathbb{S}^1_j \text{ and an } \mathbb{S}^1_j.$

The approach we take to solve both problems has two steps. The first step eliminates cancellation due to two submanifolds in \mathbb{R}^n with opposite orientation. We endow the double cover with a canonical orientation. So for example if a submanifold is a Möbius band, its double cover union boundary lift will be a torus. The orientation on the lift is not inherited from the underlying submanifold in \mathbb{R}^n . The second step is eliminate cancellation due to degree zero Gauss maps under homothetic contraction to a point of the submanifold in \mathbb{R}^n . This means we must eliminate tori. We do this by adding topological cylinders so that the result is a union of \mathbb{S}^{n-1} .

$$\widetilde{\mathbf{M}}_{\mathbf{F}} \cup \begin{pmatrix} \bigcup_{i=1}^{n} \mathbb{S}_{i}^{n-1} \end{pmatrix} = \bigcup_{j=1}^{m} \mathbb{S}_{j}^{n-1}$$

The induced orientation from step 1 applied to the extra parts of the lift will have the orientation on each \mathbb{S}^{n-1} that will ensure a degree one Gauss map under

homothetic contraction. Thus both mass elimination problems are solved. See figure 8.

We need to check that the extra mass added with the union of $\mathbb{S}^{n-1}s$ is uniformly bounded for a subsequence of lifts. $\widetilde{\mathbf{M}}_{\mathbf{Fi}}$. We need to start with a lemma:

Lemma 5.2. There exists a polyhedral n-2 skeleton S_k of parts of great spheres on \mathbb{S}^{n-1} such that its pull-back to the lifts, \widetilde{M}_i s (under the projection map $g:\mathbb{R}^nX\mathbb{S}^{n-1}\to\mathbb{S}^{n-1}$), will be of uniformly bounded n-2 Hausdorff measure, and that the diameter of each n-1 cell in \mathbb{S}^{n-1} - S_k is less than 1.

Proof. This proof uses the coarea formula to express the (n-1) volume of an \widetilde{M}_i in terms of the (n-2) volume of co-dimension one sets on $\widetilde{M}_i s$. The codimension one sets form a disjoint 1-parameter family that sweeps out to cover part of the volume of \widetilde{M}_i . In this case the choice of 1-parameter family and the fact that \widetilde{M}_i is a lift ensures that the sweep rate is at least one. The volume of \widetilde{M}_i is finite. Therefore the (n-2) volume of the codimension one sets will be uniformly bounded away from some set of measure $\varepsilon > 0$ in the 1-parameter family. Otherwise the swept out volume of \widetilde{M}_i would be too great. This proves that there must be candidates for the positions of the arcs of the skeleton S_k .

Take a family, parameterized by t of great spheres passing through the point p on the \mathbb{S}^{n-1} . Each great sphere corresponds to a fixed t, and is parameterized by \mathbf{x} . In the center of figure 7 parts of two such great spheres are shown from g(a) to g(d) and g(b) to g(c). Now remove two neighborhoods of p and its antipode from the family of spheres. The family of spheres now lies in the region shown by g(a), g(b), g(c), and g(d).

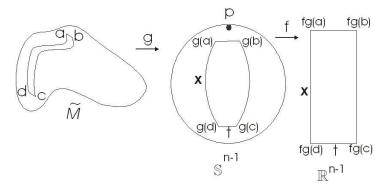


Figure 9

Now apply the coarea formula on the projection map to the pre-image of the great sphere sections parametrized by t in \widetilde{M} . We need to map from \mathbb{R}^{n-1} to \mathbb{R} , this is projection p into the t coordinate. $(pfg)^{-1}(t)$ will be the pre-image in \widetilde{M} of all points with the given t value over the values of \mathbf{x} . For example the arcs ad and bc in \widetilde{M} are each pre-images for the max and min values of t. The coarea formula [MF: p30][S: p53][F1: 3.2] is:

(5.1)
$$\int_{\widetilde{M}} J_{pfg} dH^{n-1} = \int_{t \in [0,1]} H^{n-2} \left((pfg)^{-1} (t) \right) dL^{1} (t)$$

We now need to find J_g , J_f and J_p in the direction orthonormal to the level sets of t. As g: $\widetilde{M} \subset \mathbb{R}^n X \mathbb{S}^{n-1} \to \mathbb{S}^{n-1}$, is a projection map, $J_g \leq 1$. We know by construction that $J_f \leq 1$, and $J_p = 1$.

 $J_{pfg} \leq 1$. So we can now write

$$\left|\widetilde{M}\right| = \int_{\widetilde{M}} dH^{n-1} \ge \int_{t \in [0,1]} H^{n-2} \left(\left(pfg \right)^{-1} (t) \right) dL^{1} \left(t \right)$$

We can conclude that $(pfg)^{-1}(t)$ is finite for almost all t. Furthermore we know that for every bounded B there will be a set of positive measure e in [0,1] for values of t where $H^{n-2}((pfg)^{-1}(t)) < B$. Let $H^{n-2}((pfg)^{-1}(t)) \ge B$ on a set of measure

s. Now we can write
$$sB \leq \left|\widetilde{M}\right|$$
, and as $e = 1 - s$, we can conclude $e = 1 - \frac{\left|\widetilde{M}\right|}{B}$.

For any fixed \widetilde{M} we can now construct the desired skeleton on \mathbb{S}^{n-1} by finding a union of arcs. Each arc is positioned transversely according to a t value for which it will have a pullback to \widetilde{M} of bounded volume.

We now need to show that we can derive a uniform bound for all \widetilde{M}_i . For this we need to pass to a subsequence. We know that for each i a portion of the interval [0,1] of finite measure, $H^{n-2}\left((pfg)^{-1}(t)\right) < B$. Now we consider the sum of the characteristic functions of these sets on [0,1]. The integral of this sum over [0,1] must be infinite. We can argue by contradiction that if there is no good direction then the sum will be finite over the whole of [0,1] which gives a contradiction. Therefore there will be at least a set of positive measure on [0,1] for values of t, where an infinite number of t shave those t s as good directions. We therefore can pass to this subsequence \widetilde{M}_{i_j} to gain the uniform bound as required.

Lemma 5.3. The pull-back of the intersections of great spheres on \mathbb{S}^{n-1} in lemma 5.1 can also be of uniformly bounded mass for a subsequence of the \widetilde{M}_i .

Proof. This follows by the same argument using the coarea formula and choice of spheres. Although the intersections have lower dimension, there is a correspondingly higher parameter family of them. So the dimensions work out in the coarea formula. As there are a finite number of codimensions we only need to take subsequences of the \widetilde{M}_i a finite number of times. Thus the process terminates to give a subsequence.

Lemma 5.4. The extra mass of the spheres added is uniformly bounded by uniform linear multiples of masses of the pull-backs in lemmas 5.1 and 5.2.

Proof. Consider a fiber in $\mathbb{R}^n X \mathbb{S}^{n-1}$ above a point in \mathbb{R}^n . Suppose it is on the pull-back of part of a great sphere as in lemma 5.1. There are two antipodal arcs on that \mathbb{S}^{n-1} which will contain antipodal points in M_F . We can connect them in \mathbb{S}^{n-1} by the extending the arcs on which they lie until they met in one direction. This will have a bounded arc length. As we move along the pull-back of the \mathbb{S}_k from lemma 5.1, we always connect the same way. This means we are connecting by adding part of a product structure, that is (the pull-back)X(an arc in \mathbb{S}^{n-1}). This means that however the pull-back may curve around, this curvature does not add to the mass of the added \mathbb{S}^{n-1} . Whatever the dimension of the fiber that is needed

for filling in, and whatever the dimension of the pull-back set of spheres or their intersections we always use a product structure to ensure that the added mass is fixed linear multiple of the mass of the pullbacks from lemmas 5.1 and 5.2.

We can now proceed to theorem 5.2.

Theorem 5.5. When the subsets of \mathbb{R}^n meet conditions 5.4.i, 5.4.ii and 5.4.iii, we can recover all collapsed dimensions in limit union of subsets of \mathbb{R}^n

Proof. To ensure we do not lose any sets under dimension collapsing under homothety we perform a surgery on the lift that makes it into a union of embedded spheres as in figure 9. We need to check this can always be done without adding more than a bounded amount of mass. Lemmas 5.1, 5.2 and 5.3 above do this.

These spheres then will have of degree of projection map of plus 1 or minus 1 depending on the orientation. We choose the orientation of the sphere so that the degree is always plus 1. We prove this can be done by showing that the projection map of an embedded sphere is isotopic to the identity. We can continuously deform the sphere in $\mathbb{R}^n X \mathbb{S}^{n-1}$ to make it convex, then contract down to a point.

Now we need to verify that this construction will give us a residual measure for both full and partial dimensional collapsing. The full collapsing case is given by the degree of projection map being 1. Now to prove the partial dimension collapsing case, You get a $\mathbb{R}^i X \mathbb{S}^{j-i}$ as a local product structure in the limit. Now apply the same isotopy argument in those dimensions which collapse under the product structure locally.

We finally need to check that this assignation of orientation does not induce dimension collapsing with homothetic contraction. At each point in $\mathbb{R}^i X \mathbb{S}^{n-1}$ the assigned orientation is canonical for each tangent plane that is a lift or a fill in in the fibre of a point. It is the canonical outward pointing vector to the \mathbb{S}^{n-1} component.

6. Summary

We have shown that under suitable uniform bounds (i.e.:

Either

 $(\it (3.3.i)~Sets~and~their~boundaries,~and~lower~dimensional~faces,~are~C^2~rectifiable.$

(3.3.ii) Sets and their boundaries, and lower dimensional faces, have uniformly bounded finite mass and finite integrals of principle curvatures (including distributional)

(3.3.iii) Sets have bounds on the integrals of the derivatives of curvature.)

 $((5.4.i)\ Sets\ and\ their\ boundaries,\ and\ lower\ dimensional\ faces,\ are\ C^2\ rectifiable.$

(5.4.ii) Sets and their boundaries, and lower dimensional faces, have uniformly bounded finite mass and finite integrals of principle curvatures (including distributional).

(5.4.iii) The topologically singular set, such as Y-singularities, must have a uniformly finite mass lift.)),

a sequence of unions of C^2 j-rectifiable subsets of \mathbb{R}^n , with dimensions j ranging from 0 to n-1, will converge to a union of rectifiable subsets of \mathbb{R}^n with dimensions

ranging from 0 to n-1, under a topology based upon the outward pointing vectors. This topology will also capture dimension collapsing.

Subsets whose lifts contain infinite H^{n-2} measure stationary non-manifold sets such as honeycombs in appendix may possibly converge only using varifold convergence on $\mathbb{R}^n X \mathbb{S}^{n-1}$. Meanwhile others subsets such as sequences of polyhedral approximations may have lifts that possibly converge only with current compactness. When all subsets are boundariless immersed manifolds, current compactness on the lifts is more general, as it does not have hypotheses (3.3.iii) that place bounds on derivatives of curvature.

7. Appendix

We give an example of a sequence of rectifiable sets with finite first variation and finite mass, but infinite homological boundary.

We will describe first variation and homological boundary.

7.1. **First Variation.** The first variation of an m-submanifold U in \mathbb{R}^n associated with a smooth compactly supported vector field \mathbf{g} on \mathbb{R}^n is:

of the a smooth compactly supported vector field
$$\mathbf{g}$$
 on \mathbb{R}^n is:
$$\int_U \mathbf{H} \cdot \mathbf{g} dH^m + \int_{\partial U} -\nu \cdot \mathbf{g} dH^{m-1}, \text{ is the total first variation where } \mathbf{H} \text{ is the mean}$$

curvature vector on U, vector ν is the inward pointing normal vector on the boundary.

Notice that at a Y-singularity where three half planes come together the first variation terms from each half plan can cancel.

7.2. **Homological Boundary.** This is the usual boundary in homology theory. It is the notion of boundary suitable for currents. It coincides with set boundary as in the first variation, but has extra terms due to orientation that may not match up. For example a Möbius band can be represented as a current with boundary. There will have to be an extra boundary component of multiplicity 2 due to the non orientability of the Möbius band.

The Y-singularities will have one homological boundary component at least for usual currents and homology. Taylor [T][MF: p105] uses currents mod n as a way of getting around this problem.

7.3. Example of varifold only convergence.

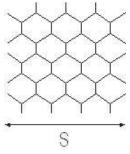


Figure 10

Consider a honeycomb, figure 10, in a cube of edge length s in \mathbb{R}^3 . It projects down to a tessellation of hexagons in the x-y plane and has height h in the z direction. Along each side of the honeycomb there are n vertical edges. This

will correspond to the order of n^2 vertical Y-singularities on the interior of the honeycomb, where three faces come together.

The total mass of the honeycomb is of the order 2nsh. As s does not affect any other quantity, we can now ignore mass.

The homological boundary mass, from the Y's is of the order of hn^2 . The first variation, from the outer ends of the honeycomb is of order 4nh. We can set up a sequence where h = 1/n of honeycombs. The first variation is uniformly bounded and the homological boundary is not.

Notice that if $h = 1/n^3$ we can take the unions of all the honeycombs and obtain a rectifiable set which can be represented as an integer multiplicity rectifiable varifold, but not as an integer multiplicity rectifiable current.

This particular example can be represented as a current mod 3, but one can easily add extra faces to the honeycomb to create an infinite measure of singularities with 3 and infinite measure with 5 faces coming together. Thus in general currents mod n do not eliminate the need for varifold compactness.

References

- [Al] Allard, William. K. On the first variation of a varifold. Ann Math 95 (1972), 417-491
- [An] Anzellotti, G. and Serapioni, R.: C^k rectifiable sets. J. Reine Angew. Math. 453, 1-20 (1994)
- [DF] Dao, Trong Thi, Fomenko, A.T. Minimal surfaces, stratified multivarifolds, and the plateau problem. Translations of mathematical monographs, AMS. vol 84 1991.
- [FF] Federer, H. and Fleming, W. Normal and integral currents, Annals of Math, 72 (1960), 458-520.
- [F1] Federer, H: Geometric measure theory. Springer-Verlag. reprinted 1996 (reprint of 1969 edition)
- [F2] Federer, H.: Curvature Measures. Transactions of the American Mathematical Society. 93, 418-419 (1959)
- [Fo] Fomenko, A.T. The Plateau Problem: Part II the present state of the theory. Chapter 4.Studies in the Development of Modern Mathematics Volume 1. Gordon and Breach 1990
- [Fu] Fu, Joseph H.G, Some remarks on Legendrian rectifiable currents. Manuscripta Mathematica, 97,175-187 (1998)
- [HS] Hardt, R. and Simon, L. Seminar on Geometric Measure Theory. Birkhauser (1986)
- [LY] Lin, F and Yang X. Geometric Measure Theory: An Introduction. International Press Boston (2002)
- [Ma] Mattila, Pertti. Geometry of Sets and Measures in Euclidean Spaces: Fractals and Rectifiability. Cambridge (1995).
- [MF] Morgan, Frank Geometric Measure Theory, a Beginners Guide. Third edition. Academic Press (2000).
- [MS] Morgan, Simon P. Harmonic Maps of Surfaces Approaching the Boundary of Moduli Space and Eliminating Bubbling. Preprint (2004) http://www.arxiv.org/ps/math.DG/0409064
- [S] Simon, Leon. Lectures on Geometric Measure Theory.
- [T] Taylor, Jean E. Regularity of the singular sets of two dimensional area minimizing flat chains modulo 3 in \mathbb{R}^3 . Invent. Math. 22(1973), 119-159.

Acknowledgements

I would like to thank Bob Hardt, my thesis advisor who suggested the approach for this work, Thierry de Pauw, Robert Gulliver, Brian White, Penny Smith, and David Johnson for their helpful discussions.

University of Minnesota E-mail address: morgan@math.umn.edu

URL: http://www.math.umn.edu/~morgan